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# IoT Based Waste Water Cleaning and Management Machine

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**ABSTRACT:** Effective waste removal in the water sources such as lakes, ponds and rivers are essential for waste management and control. In Indian setting, Aquatic waste management and control is of main concern for implementing smart city and achieving clean India mission. Therefore, the proposed work, aims at developing intelligent solution towards automating the waste removal in lakes. Lake cleaning robot system for removing the surface wastes is experimented in this work. This wireless system consists of a transmitter application that runs on an android mobile app which allows the robot to follow commands given by the user through the transmitter app. The proposed solar based robot consists of Arduino UNO controller which has fourteen digital input/output pins, robotic arm with cleaning pad with a water sprayer for efficient cleaning. his tool works when the Arduino Uno microcontroller processes the gas sensor detector and a DC motor as a robot driver, then the DC motor is driven by the Motor Shield L298. The Arduino UNO, on receiving the commands from android device through WIFI module, decodes the given commands and controls the motors to achieve the desired path and direction to do the work easily we have developed the robot & it is designed in such a way that it can clean house, offices, apartments, cellars, and even streets as well. The person who is standing far gone of the cleaning area is monitoring the robot.

## I.INTRODUCTION

Robotics is part of Today's communication. In today's world ROBOTICS is fast growing and interesting field. It is simplest way for latest technology modification. Now a day's communication is part of advancement of technology, so we decided to work on robotics field, and design something which will make human life simpler in day today aspect. Thus, we are supporting this cause. Robotics is the branch of technology that deals with the design, construction, operation, structural disposition, manufacture and application of robots and computer systems for their control, sensory feedback, and information processing. In the recent years, robots have been used for various cleaning purposes. Robots have various cleaning expertise like mopping, picking up the waste, wet floor cleaning, dry vacuum cleaning etc., Depending on the cleaning mechanism, these robots may have some advantages and disadvantages. Smart floor cleaning robot has been designed for home and office environments. This robot will be using water storage with anti-infection solution which is pumped with water pump motor. This robot on receiving the commands from the android device cleans an area using a cleaning pad by spraying water on the floor. After cleaning the wet floor, it can drain the dirty water into the required container as per the commands given to it. The robotic arm is used for efficient and effective wet floor cleaning purpose.

This system can also be used to pick up the objects and carry them within the Bluetooth range. The proposed system is a manual system because it is controlled by android application which is operated by human. In this project mainly whenever robot senses any obstacle automatically diverts its position to left or right and follows the path. Robot consists of two motors, which control the side pair wheels of each and help in moving forward and backward direction. Robot senses the object with help of obstacle sensor. IR pair is used for detecting the obstacle. The two basic parts for working with IR are the emitter and the detector. The emitter is typically an LED that emits near-infrared light. Infrared (IR) light is electromagnetic radiation with a wavelength longer than that of visible light, measured from the nominal edge of visible red light at 0.74 micrometers ( $\mu\text{m}$ ), and extending conventionally to 300  $\mu\text{m}$ . These wavelengths correspond to a frequency range of approximately 1 to 400 THz, and include most of the thermal radiation emitted by objects near room temperature. Microscopically, IR light is typically emitted or absorbed by molecules

when they change their rotational-vibration movements. Infrared light is used in industrial, scientific, and medical applications.

Night-vision devices using infrared illumination allow people or animals to be observed without the observer being detected. In astronomy, imaging at infrared wavelengths allows observation of objects obscured by interstellar dust. Infrared imaging cameras are used to detect heat loss in insulated systems, observe changing blood flow in the skin, and overheating of electrical apparatus. IR LED IR detectors are specially filtered for Infrared lighted are not good at detecting visible light. On the other hand, photocells are good at detecting yellow/green visible light, not well at IR light IR detectors have a demodulator inside that looks for modulated IR at 38 KHz. Photocells do not have any sort of demodulator and can detect any frequency (including DC) within the response speed of the photocell. IR detectors are digital out - either they detect 38KHz IR signal and output low (0V) or they do not detect any and output high (5V). Photocells act like resistors, the resistance changes depending on how much light they are exposed.

A photodiode is a type of photo detector capable of converting light into either current or voltage, depending upon the mode of operation. The common, traditional solar cell used to generate electric solar power is a large area photodiode. Photodiodes are similar to regular semiconductor diodes except that they may be either exposed (to detect vacuum UV or X-rays) or packaged with a window or optical fiber connection to allow light to reach the sensitive part of the device.

## **II.EXISTING SYSTEM**

A robot vacuum cleaner is a type of autonomous robotic vacuum cleaner that can clean the floor without requiring any human intervention. This robot vacuum cleaner has various features that make it suitable for different cleaning tasks, such as spinning brushes that sweep the dust, mopping that wipes the floor, UV sterilization that kills the germs, and security cameras that monitor the surroundings. However, this robot vacuum cleaner also has some limitations, such as colliding with obstacles and stopping at a short distance from walls and other objects, which prevent it from reaching all the corners and edges of the room and leave some areas unclean. Another type of robot that can clean the floor is an automatic floor cleaner robot, which has brushes attached to its sides to collect the dust. This robot uses ultrasonic sensors to detect and avoid obstacles and change its direction accordingly. It also has a suction unit that sucks in the dust while moving around the room freely. However, this robot cannot clean the wet floor, which is a disadvantage for some situations. A third type of robot that can perform cleaning tasks is a metallic waste collection robot, which was proposed for automating waste removal in factories. This robot is an end-to-end robotic system that uses Arduino Mega micro controller as the main controller, which is interfaced with various sensors and actuators. The robot has grippers that can pick up the metallic waste, motors that power the wheels, and chassis that support the structure. The robot also has object detection and sensing capabilities, which are done using IR and ultrasonic sensors. These sensors help the robot to navigate the environment and locate the waste.

## **III.PROPOSED SYSTEM**

In proposed system robot is Design and Implementation of Cleaning Robot using Android App” for better understanding of the proposed work. This lake cleaning system uses Arduino along with proximity sensors for detection and DC motors for movement. When the sensor detects static obstacle, the rotating blades start and the garbage is pushed into a bin which is placed right behind the mechanism. The performance of the baseline prototype model of the proposed system tested in a real time emulated environment, justifies the use of lake cleaning robot towards control and management of aquatic waste. This block diagram consists of 12v DC motor, L293D IC, WIFI module, cleaning mechanism and Arduino UNO. The power supply is given to the Arduino UNO as well as to relay. The relay works as switch so that it controls the cleaning mechanism whenever the user receives the commands from transmitter app.

#### IV.HARDWARE DESCRIPTION

##### ARDUINO UNO R3 MICROCONTROLLER



Figure.1.Arduino UNO

Arduino Nano controls the other components Raspberry Pi, motors, motor driver module, ultrasonic sensor.

##### RELAY

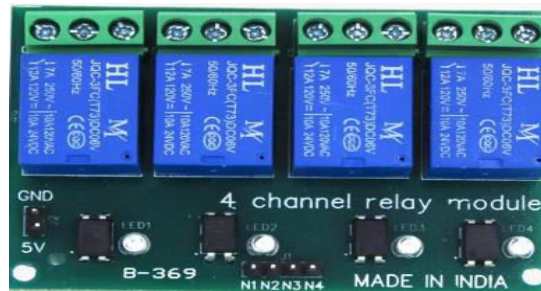


Figure.2.Channel Relay Module

A 4-channel relay module is a device that allows you to control four high-voltage or high-current devices with low-voltage signals from a microcontroller such as Arduino, ESP32, or Raspberry Pi. You can use a 4-channel relay module to switch on or off devices like lamps, motors, solenoids, or AC loads. To use a 4-channel relay module, you need to connect the power pins (DC+ and DC-) to an external 5V power supply, and the signal pins (IN1, IN2, IN3, and IN4) to the digital output pins of your microcontroller. You also need to connect the output pins (Nc x, NOx, and COM x) to the devices you want to control, depending on whether you want them to be normally open or normally closed.

##### DC MOTOR



Figure.3.DC Gear Motor

The DC Gear Motor was moved to the rover forward, backward, left, and right.

##### WIFI Controller

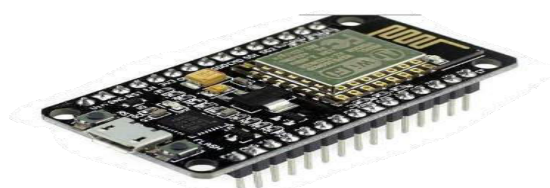


Figure.4.WI-FI NODE MCU ESP8266

WI-FI NODEMCU Esp8266 is a development board that combines the ESP8266 Wi-Fi module with a microcontroller and a USB interface. You can use it to create various Wi-Fi projects, such as web servers, web clients, IoT devices, robots, and more. You can program it using the Arduino IDE or other compatible software. To use the WI-FI NODEMCU Esp8266, you need to install the ESP8266 board package in the Arduino IDE and select the Node MCU 1.0 (ESP-12E Module) as the board. You also need to install the appropriate drivers for your operating system to recognize the board. You can find more information on how to set up the WI-FI NODEMCU Esp8266 in this tutorial. Depending on your project, you may also need to connect some sensors, actuators, or other components to the WI-FI NODEMCU Esp8266. The board has several GPIO pins that you can use to interface with other devices.

**BATTERY**

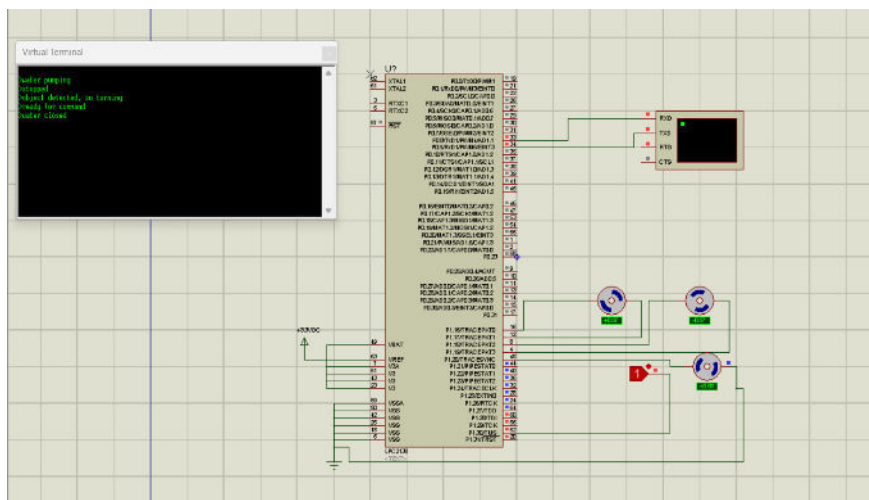


**Figure.5.12 V 1 AMP Battery**

A 12 V 1 AMP battery is a type of rechargeable battery that can provide 12 volts of direct current and store 1 ampere-hour of electric charge. You can use a 12 V 1 AMP battery to power various devices that require 12 volts and low current, such as LED lights, small motors, sensors, or controllers.

**V.SIMULATION RESULT**

An embedded system is an application that contains at least one programmable computer (typically in the form of a microcontroller, a microprocessor or digital signal processor chip) and which is used by individuals who are, in the main, unaware that the system is computer-based.



**Figure.6.Simulation Result**

The ISIS Intelligent Schematic Input System (Intelligent Switching input system), is the environment for the design and simulation of electronic circuits. The component library includes claims more than 10,000 circuit components with 6000 Prospect Simulations models. The VSM Virtual System Modeling provides a graphical SPICE circuit simulation and animation directly in the ISIS environment. The SPICE simulator is based on the Berkeley SPICE3F5 model.

## VI.HARDWARE RESULT

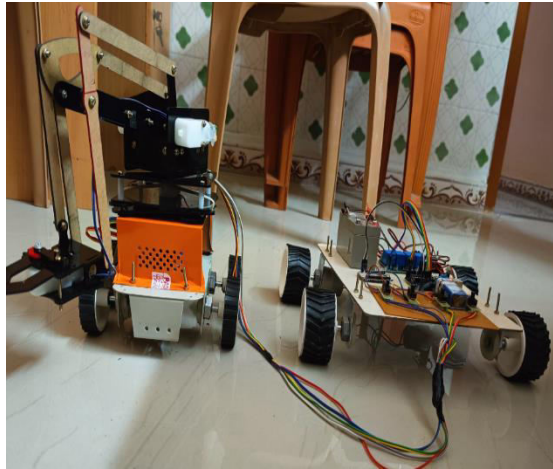


Figure.7.Hardware Diagram

Waste water cleaning machines play a significant role in environmental conservation efforts, ensuring cleaner public spaces and healthier aquatic ecosystems. These machines are continually evolving with advanced sensor technologies, making them more efficient and capable of addressing complex environmental challenges.

## VII.CONCLUSION

A lake cleaning robot to remove surface wastes and garbage is proposed in this work. The proposed hardware consists of an Arduino board to control the movement of the robot along with gripper, motors, ultrasonic sensor. The developed lake cleaning robot can be used in all lakes and other static water bodies to clean the plastic and other floating wastes. This helps in decreasing the water pollution and thus providing a balanced environment and ecosystem. The more developed future product can also be made to work in flowing waters.

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